Universal by Mitchell J. Feigenbaum Behavior in Nonlinear Systems

Universal numbers, $\delta = 4.6692016...$

and

α = 2.502907875...,
 determine quantitatively the transition from smooth to turbulent or erratic behavior for a large class of nonlinear systems.

■ here exist in nature processes that can be described as complex or chaotic and processes that are simple or orderly. Technology attempts to create devices of the simple variety: an idea is to be implemented, and various parts executing orderly motions are assembled. For example, cars, airplanes, radios, and clocks are all constructed from a variety of elementary parts each of which, ideally, implements one ordered aspect of the device. Technology also tries to control or minimize the impact of seemingly disordered processes, such as the complex weather patterns of the atmosphere, the myriad whorls of turmoil in a turbulent fluid, the erratic noise in an electronic signal, and other such phenomena. It is the complex phenomena that interest us

When a signal is noisy, its behavior from moment to moment is irregular and has no simple pattern of prediction. However, if we analyze a sufficiently long record of the signal, we may find that signal amplitudes occur within narrow ranges a definite fraction of the time. Analysis of another record of the signal may reveal the same fraction. In this case, the noise can be given a statistical description. This means that while it is impossible to say what amplitude will appear next in succession, it is possible to estimate the probability or likelihood that the signal will attain some specified range of values. Indeed, for the last hundred years disorderly processes have been taken to be statistical (one has

given up asking for a precise causal prediction), so that the goal of a description is to determine what the probabilities are, and from this information to determine various behaviors of interest—for example, how air turbulence modifies the drag on an airplane.

We know that perfectly definite causal and simple rules can have statistical (or random) behaviors. Thus, modern computers possess "random number generators" that provide the statistical ingredient in a simulation of an erratic process. However, this generator does nothing more than shift the decimal point in a rational number whose repeating block is suitably long. Accordingly, it is possible to predict what the nth generated number will be. Yet, in a list of successive generated numbers there is such a seeming lack of order that all statistical tests will confer upon the numbers a pedigree of randomness. Technically, the term "pseudorandom" is used to indicate this nature. One now may ask whether the various complex processes of nature themselves might not be merely pseudorandom, with the full import of randomness, which is untestable, a historic but misleading concept. Indeed our purpose here is to explore this possibility. What will prove altogether remarkable is that some very simple schemes to produce erratic numbers behave identically to some of the erratic aspects of natural phenomena. More specifically, there is now cogent evidence that the problem of how a fluid changes over from smooth to turbulent flow can be solved through its relation to the simple scheme described in this article. Other natural problems that can be treated in the same way are the behavior of a population from generation to generation and the noisiness of a large variety of mechanical, electrical, and chemical oscillators. Also, there is now evidence that various Hamiltonian systems—those subscribing to classical mechanics, such as the solar system—can come under this discipline.

The feature common to these phenomena is that, as some external parameter (temperature, for example) is varied, the behavior of the system changes from simple to erratic. More precisely, for some range of parameter values, the system exhibits an orderly periodic behavior; that is, the system's behavior reproduces itself every period of time T. Beyond this range, the behavior fails to reproduce itself after T seconds; it almost does so, but in fact it requires two intervals of T to repeat itself. That is, the period has doubled to 2T. This new periodicity remains over some range of parameter values until another critical parameter value is reached after which the behavior almost reproduces itself after 2T, but in fact, it now requires 4T for reproduction. This process of successive period doubling recurs continually (with the range of parameter values for which the period is 2ⁿT becoming successively smaller as n increases) until, at a certain value of the parameter, it has doubled ad infinitum, so that the behavior is no longer periodic. Period doubling is then a characteristic route for a system to follow as it changes over from simple periodic to complex aperiodic motion. All the phenomena mentioned above exhibit period doubling. In the limit of aperiodic behavior, there is a unique and hence universal solution common to all systems undergoing period doubling. This fact implies remarkable consequences. For a given system, if we denote by \wedge_n the value of the parameter at which its period doubles for the nth time, we find that the values \wedge_n converge to \wedge_{∞} (at which the motion is aperiodic) geometrically for large n. This means that

$$\Lambda_{m} - \Lambda_{n} \propto \delta^{-n} \tag{1}$$

for a fixed value of δ (the *rate* of onset of complex behavior) as n becomes large. Put differently, if we define

$$\delta_{n} \equiv \frac{\Lambda_{n+1} - \Lambda_{n}}{\Lambda_{n+2} - \Lambda_{n+1}} , \qquad (2)$$

 δ_n (quickly) approaches the constant value δ . (Typically, δ_n will agree with δ to several significant figures after just a few period doublings.) What is quite remarkable (beyond the fact that there is always a geometric convergence) is that, for all systems undergoing this period doubling, the value of δ is *predetermined* at the universal value

$$\delta = 4.6692016 \dots . (3)$$

Thus, this definite number must appear as a natural rate in oscillators, populations, fluids, and all systems exhibiting a period-doubling route to turbulence! In fact, most measurable properties of any such system in this aperiodic limit now can be determined, in a way that essentially bypasses the details of the equations governing each specific system because the theory of this behavior is universal over such details. That is, so long as a system possesses certain qualitative properties that enable it to undergo this route to complexity, its quantitative properties are determined. (This result is analogous to the results of the modern theory of critical phenomena, where a few qualitative properties of the system undergoing a phase transition, notably the dimensionality, determine universal critical exponents. Indeed at a *formal* level the two theories are identical in that they are fixed-point theories, and the number δ , for example, can be viewed as a critical exponent.) Accordingly, it is sufficient to study the simplest system exhibiting this phenomenon to comprehend the general case.

Functional Iteration

A random number generator is an example of a simple iteration scheme that has complex behavior. Such a scheme generates the next pseudorandom number by a definite transformation upon the present pseudorandom number. In other words, a certain function is reevaluated successively to produce a sequence of such numbers. Thus, if f is the function and x_0 is a starting number (or "seed"), then x_0 , x_1 , ..., x_n , ..., where

is the sequence of generated pseudorandom numbers. That is, they are generated by *functional iteration*. The nth element in the sequence is

$$x_n = f(f(... f(f(x_0)) ...)) \equiv f^n(x_0),$$
 (5)

where n is the total number of applications of f. $[f^n(x)]$ is not the nth power of f(x); it is the nth *iterate* of f.] A property of iterates worthy of mention is

$$f^{n}(f^{m}(x)) = f^{m}(f^{n}(x)) = f^{m+n}(x),$$
 (6)

since each expression is simply m + n applications of f. It is understood that

$$f^0(x) = x. (7)$$

It is also useful to have a symbol, \circ , for functional iteration (or composition), so that

$$f^n \circ f^m = f^m \circ f^n = f^{m+n}$$
. (8)

Now f^n in Eq. (5) is itself a definite and computable function, so that x_n as a function of x_0 is known in principle.

If the function f is *linear* as, for example,

$$f(x) = ax (9)$$

for some constant a, it is easy to see that

$$f^{n}(x) = a^{n}x, \qquad (10)$$

so that, for this f.

$$x_n = a^n x_0 \tag{11}$$

is the solution of the recurrence relation defined in Eq. (4),

$$\mathbf{x}_{n+1} = \mathbf{a}\mathbf{x}_{n} \,. \tag{12}$$

Should |a| < 1, then x_n geometrically converges to zero at the rate 1/a. This example is special in that the linearity of f allows for the explicit computation of f^n .

We must choose a *nonlinear* f to generate a pseudorandom sequence of numbers. If we choose for our nonlinear

$$f(x) = a - x^2, (13)$$

then it turns out that f^n is a polynominal in x of order 2^n . This polynomial rapidly becomes unmanageably large; moreover, its coefficients are polynomials in a of order up to 2^{n-1} and become equally difficult to compute. Thus even if $x_0 = 0$, x_n is a polynomial in a of order 2^{n-1} . These polynomials are nontrivial as can be surmised from the fact that for certain

values of a, the sequence of numbers generated for almost all starting points in the range $(a - a^2,a)$ possess all the mathematical properties of a random sequence. To illustrate this, the figure on the cover depicts the iterates of a similar system in two dimensions:

$$x_{n+1} = y_n - x_n^2$$

 $y_{n+1} = a - x_n$. (14)

Analogous to Eq. (4), a starting coordinate pair (x_0,y_0) is used in Eq. (14) to determine the next coordinate (x_1,y_1) . Equation (14) is reapplied to determine (x_2,y_2) and so on. For some initial points, all iterates lie along a definite elliptic curve, whereas for others the iterates are distributed "randomly" over a certain region. It should be obvious that no explicit formula will account for the vastly rich behavior shown in the figure. That is, while the iteration scheme of Eq. (14) is trivial to specify, its nth iterate as a function of (x_0, y_0) is unavailable. Put differently, applying the simplest of nonlinear iteration schemes to itself sufficiently many times can create vastly complex behavior. Yet, precisely because the same operation is reapplied, it is conceivable that only a select few selfconsistent patterns might emerge where the consistency is determined by the key notion of iteration and not by the particular function performing the iterates. These self-consistent patterns do occur in the limit of infinite period doubling and in a well-defined intricate organization that can be determined a priori amidst the immense complexity depicted in the cover figure.

The Fixed-Point Behavior of Functional Iterations

Let us now make a direct onslaught against Eq. (13) to see what it possesses. We want to know the behavior of the system after many iterations. As we already know, high iterates of f rapidly become very complicated. One way this growth can be prevented is to have the first iterate of x_0 be precisely x_0 itself. Generally, this is impossible. Rather this condition *determines* possible x_0 's. Such a self-reproducing point is called a *fixed* point of f. The sequence of iterates is then x_0 , x_0 , x_0 , ... so that the behavior is static, or if viewed as periodic, it has period 1.

It is elementary to determine the fixed points of Eq. (13). For future convenience we shall use a modified form of Eq. (13) obtained by a translation in x and some redefinitions:

$$f(x) = 4\lambda x(1-x), \qquad (15)$$

so that as λ is varied, x = 0 is always a fixed point. Indeed, the fixed-point condition for Eq. (15),

$$x^* = f(x^*) = 4\lambda x^*(1 - x^*),$$
 (16)

gives as the two fixed points

$$x^* = 0, x_0^* = 1 - 1/4\lambda$$
. (17)

The maximum value of f(x) in Eq. (15) is attained at $x = \frac{1}{2}$ and is equal to λ . Also, for $\lambda > 0$ and x in the interval (0,1), f(x) is always positive. Thus, if λ is anywhere in the range [0,1], then any iterate of any x in (0,1) is also always in (0,1). Accordingly, in all that follows we shall consider only values of x and λ lving between 0 and 1. By Eq. (16) for $0 \le$ $\lambda < \frac{1}{4}$, only $x^* = 0$ is within range, whereas for $\frac{1}{4} \le \lambda \le 1$, both fixed points are within the range. For example, if we set $\lambda = \frac{1}{2}$ and we start at the fixed point $x_0^* = \frac{1}{2}$ (that is, we set $x_0 = \frac{1}{2}$), then $x_1 = \frac{1}{2}$ $x_2 = ... = \frac{1}{2}$; similarly if $x_0 = 0$, $x_1 = x_2$ = ... = 0, and the problem of computing the nth iterate is obviously trivial.

What if we choose an x_0 not at a fixed point? The easiest way to see what happens is to perform a graphical analysis. We graph y = f(x) together with y = x.

Where the lines intersect we have x = y = f(x), so that the intersections are precisely the fixed points. Now, if we choose an x_0 and plot it on the x-axis, the ordinate of f(x) at x_0 is x_1 . To obtain x_2 , we must transfer x_1 to the x-axis before reapplying f. Reflection through the straight line y = x accomplishes precisely this operation. Altogether, to iterate an initial x_0 successively,

- 1. move vertically to the graph of f(x),
- 2. move horizontally to the graph of y = x, and
- 3. repeat steps 1, 2, etc.

Figure 1 depicts this process for $\lambda = \frac{1}{2}$. The two fixed points are circled, and the first several iterates of an arbitrarily chosen point x_0 are shown. What should be obvious is that if we start from any x_0 in (0,1) (x = 0 and x = 1 excluded), upon continued iteration x_n will converge to the fixed point at $x = \frac{1}{2}$. No matter how close x_0 is to the fixed point at x = 0, the iterates diverge away from it. Such a fixed point is termed unstable. Alternatively, for almost all x₀ near enough to $x = \frac{1}{2}$ [in this case, all x_0 in (0,1)], the iterates converge towards $x = \frac{1}{2}$. Such a fixed point is termed stable or is referred to as an attractor of period 1.

Now, if we don't care about the transient behavior of the iterates of x₀, but only about some regular behavior that will emerge eventually, then knowledge of the stable fixed point at $x = \frac{1}{2}$ satisfies our concern for the eventual behavior of the iterates. In this restricted sense of eventual behavior, the existence of an attractor determines the solution independently of the initial condition x_0 provided that x_0 is within the basin of attraction of the attractor; that is, that it is attracted. The attractor satisfies Eq. (16), which is explicitly independent of x₀. This condition is the basic theme of universal behavior: if an attractor exists, the eventual behavior is independent of the starting point.

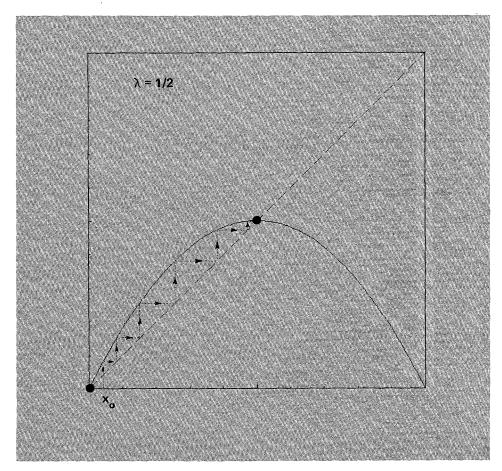


Fig. 1. Iterates of x_0 at $\lambda = 0.5$.

What makes x = 0 unstable, but $x = \frac{1}{2}$ stable? The reader should be able to convince himself that x = 0 is unstable because the slope of f(x) at x = 0 is greater than 1. Indeed, if x^* is a fixed point of f and the derivative of f at x^* , $f'(x^*)$, is smaller than 1 in absolute value, then x^* is stable. If $|f'(x^*)|$ is greater than 1, then x^* is unstable. Also, only stable fixed points can account for the eventual behavior of the iterates of an arbitrary point.

We now must ask, "For what values of λ are the fixed points attracting?" By Eq. (15), $f'(x) = 4\lambda(1-2x)$ so that

$$f'(0) = 4\lambda \tag{18}$$

and

$$f'(x_0^*) = 2 - 4\lambda.$$
 (19)

For $0 < \lambda < \frac{1}{4}$, only $x^* = 0$ is stable. At $\lambda = \frac{1}{4}$, $x_0^* = 0$ and $f'(x_0^*) = 1$. For $\frac{1}{4} < \lambda < \frac{3}{4}$, x^* is unstable and x_0^* is stable, while at $\lambda = \frac{3}{4}$, $f'(x_0^*) = -1$ and x_0^* also has become unstable. Thus, for $0 < \lambda < \frac{3}{4}$, the eventual behavior is known.

Period 2 from the Fixed Point

What happens to the system when λ is in the range $\frac{3}{4} < \lambda < 1$, where there are no attracting fixed points? We will see that as λ increases slightly beyond $\lambda =$ $\frac{3}{4}$, f undergoes period doubling. That is, instead of having a stable cycle of period 1 corresponding to one fixed point, the system has a stable cycle of period 2; that is, the cycle contains two points. Since these two points are fixed points of the function f² (f applied twice) and since stability is determined by the slope of a function at its fixed points, we must now focus on f². First, we examine a graph of f^2 at λ just below $\frac{3}{4}$. Figures 2a and b show f and f^2 , respectively, at $\lambda = 0.7$.

To understand Fig. 2b, observe first that, since f is symmetric about its maximum at $x = \frac{1}{2}$, f^2 is also symmetric about $x = \frac{1}{2}$. Also, f^2 must have a fixed point whenever f does because the second iterate of a fixed point is still that same point. The main ingredient that determines the period-doubling behavior of f as λ increases is the relationship of the slope of f^2 to the slope of f. This relationship is a consequence of the chain rule. By definition

$$x_2 = f^2(x_0) ,$$

where

$$x_1 = f(x_0), x_2 = f(x_1).$$

We leave it to the reader to verify by the chain rule that

$$f^{2}(x_{0}) = f'(x_{0})f'(x_{1})$$
(20)

and

$$f^{n}(x_0) = f'(x_0)f'(x_1) \dots f'(x_{n-1}),$$
 (21)

an elementary result that determines period doubling. If we start at a fixed point of f and apply Eq. (20) to $x_0 = x^*$, so that $x_2 = x_1 = x^*$, then

$$f^{2}(x^*) = f'(x^*)f'(x^*) = [f'(x^*)]^2$$
. (22)

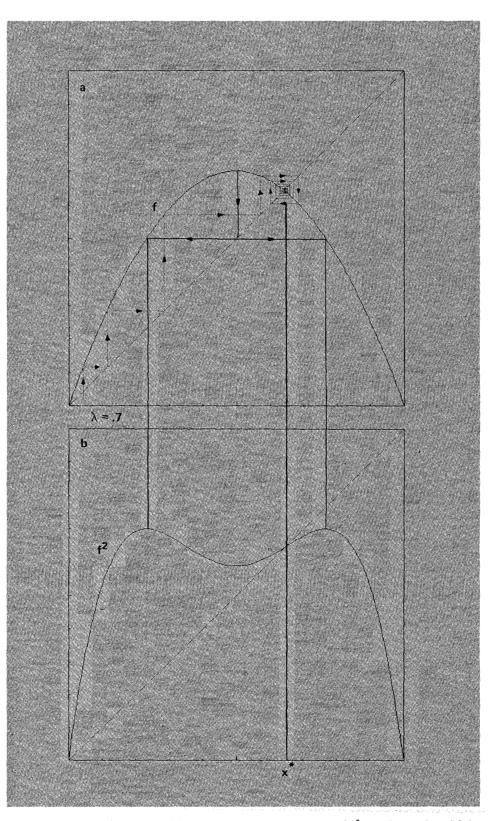


Fig. 2. $\lambda = 0.7$. x^* is the stable fixed point. The extrema of f^2 are located in (a) by constructing the inverse iterates of x = 0.5.

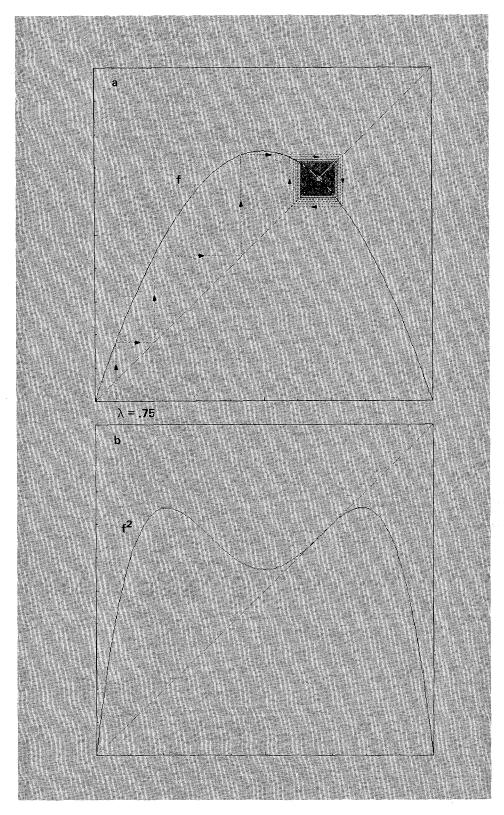


Fig. 3. $\lambda = 0.75$. (a) depicts the slow convergence to the fixed point. f^2 osculates about the fixed point.

Since at $\lambda = 0.7$, $|f'(x^*)| < 1$, it follows from Eq. (22) that

$$0 < f^{2}(x^{*}) < 1$$
.

Also, if we start at the extremum of f, so that $x_0 = \frac{1}{2}$ and $f'(x_0) = 0$, it follows from Eq. (21) that

$$f^{n} {\binom{1}{2}} = 0 (23)$$

for all n. In particular, f2 is extreme (and a minimum) at $\frac{1}{2}$. Also, by Eq. (20), f^2 will be extreme (and a maximum) at the x_0 that will iterate under f to $x = \frac{1}{2}$, since then $x_1 = \frac{1}{2}$ and $f'(x_1) = 0$. These points, the *inverses* of $x = \frac{1}{2}$, are found by going vertically down along $x = \frac{1}{2}$ to y = xand then horizontally to y = f(x). (Reverse the arrows in Fig. 1, and see Fig. 2a.) Since f has a maximum, there are two horizontal intersections and, hence, the two maxima of Fig. 2b. The ability of f to have complex behaviors is precisely the consequence of its doublevalued inverse, which is in turn a reflection of its possession of an extremum. A monotone f, one that always increases, always has simple behaviors, whether or not the behaviors are easy to compute. A linear f is always monotone. The f's we care about always fold over and so are strongly nonlinear. This folding nonlinearity gives rise to universality. Just as linearity in any system implies a definite method of solution, folding nonlinearity in any system also implies a definite method of solution. In fact folding nonlinearity in the aperiodic limit of period doubling in any system is solvable, and many systems, such as various coupled nonlinear differential equations, possess this nonlinearity.

To return to Fig. 2b, as $\lambda \to \frac{3}{4}$ and the maximum value of f increases to $\frac{3}{4}$, $f'(x^*) \to -1$ and $f^{2\prime}(x^*) \to +1$. As λ increases beyond $\frac{3}{4}$, $|f'(x^*)| > 1$ and $f^{2\prime}(x^*) > 1$, so that f^2 must develop two new fixed points beyond those of f; that is, f^2 will cross y = x at two more points. This transition is depicted in Figs. 3a and b for f and f^2 , respectively, at $\lambda =$